

LAMPIRAN

Lampiran 1 : Script Matlab Pengambilan Data Normal

%Script to run data acquisition using National Instrument NI 9234

%Created: Juli 2018, Rifasakin.

clear;

clc;

close all;

tic;

s = daq.createSession('ni');

s.DurationInSeconds = 5;

Dur = s.DurationInSeconds;

s.Rate = 25600;

s.addAnalogInputChannel('cDAQ1Mod1', 'ai0', 'Accelerometer');

%s.addAnalogInputChannel('cDAQ1Mod1', 'ai1', 'Accelerometer');

%s.addAnalogInputChannel('cDAQ1Mod1', 'ai2', 'Accelerometer');

s.addAnalogInputChannel('cDAQ1Mod1', 'ai3', 'Voltage'); % Tachometer

%s.addAnalogInputChannel('cDAQ1Mod2', 'ai0', 'Microphone');

%s.addAnalogInputChannel('cDAQ1Mod2', 'ai1', 'Microphone');

s.Channels(1).Sensitivity = 97.60E-3; %mV/g Type 4507B serial:11165

%s.Channels(2).Sensitivity = 95.83E-3; %mV/g Type 4507B serial:11026

%s.Channels(3).Sensitivity = 99.56E-3; %mV/g Type 4507B serial:10984

%s.Channels(4).Sensitivity = 94.50E-3;

%s.Channels(5).Sensitivity = 9.40E-3; %mV/Pa Model 130B40 serial:41741

%s.Channels(6).Sensitivity = 8.60E-3; %mV/Pa Model 130B40 serial:41842

for i=1:50

```

data = s.startForeground();      % start recording vibration data
data_ch1 = data(:,1);
data_ch2 = data(:,2);
%data_ch3 = data(:,3);
%data_ch4 = data(:,4);
%data_ch5 = data(:,5);
%data_ch6 = data(:,6);

rootname = 'E:\Pengambilan_Data_TA'; % drive tujuan dan nama file
extension = '.mat'; % ekstension utk nama file
namafile = [rootname,'SignalBearing',num2str(i),extension];
data_all = [data_ch1 data_ch2 ];
eval(['save ', namafile , ' data_all']);

pause(3)
pesan = ['Acquiring and saving data at loop number: ',num2str(i)];
disp(pesan)
end

```

toc

rootname : diganti tempat yang digunakan untuk menyimpan file.

Lampiran 2 : Script Matlab Pengambilan data cacat elemen bola

```

%Script to run data acquisition using National Instrument NI 9234
%Created: Juli 2018, Rifasakin.

```

```

clear;
clc;
close all;

```

```

tic;

s = daq.createSession('ni');
s.DurationInSeconds = 5;
Dur = s.DurationInSeconds;
s.Rate = 25600;
s.addAnalogInputChannel('cDAQ1Mod1', 'ai0', 'Accelerometer');
%s.addAnalogInputChannel('cDAQ1Mod1', 'ai1', 'Accelerometer');
%s.addAnalogInputChannel('cDAQ1Mod1', 'ai2', 'Accelerometer');
s.addAnalogInputChannel('cDAQ1Mod1', 'ai3', 'Voltage'); % Tachometer
%s.addAnalogInputChannel('cDAQ1Mod2', 'ai0', 'Microphone');
%s.addAnalogInputChannel('cDAQ1Mod2', 'ai1', 'Microphone');

s.Channels(1).Sensitivity = 97.60E-3; %mV/g Type 4507B serial:11165
%s.Channels(2).Sensitivity = 95.83E-3; %mV/g Type 4507B serial:11026
%s.Channels(3).Sensitivity = 99.56E-3; %mV/g Type 4507B serial:10984
%s.Channels(4).Sensitivity = 94.50E-3;
%s.Channels(5).Sensitivity = 9.40E-3; %mV/Pa Model 130B40 serial:41741
%s.Channels(6).Sensitivity = 8.60E-3; %mV/Pa Model 130B40 serial:41842

for i=1:50

data = s.startForeground(); % start recording vibration data
data_ch1 = data(:,1);
data_ch2 = data(:,2);
%data_ch3 = data(:,3);
%data_ch4 = data(:,4);
%data_ch5 = data(:,5);
%data_ch6 = data(:,6);

```

```

rootname = 'E:\Pengambilan_Data_TA'; % drive tujuan dan nama file
extension = '.mat'; % ekstension utk nama file
namafile = [rootname,'CacatBola',num2str(i),extension];
data_all = [data_ch1 data_ch2 ];
eval(['save ', namafile , ' data_all']);

pause(3)
pesan = ['Acquiring and saving data at loop number: ',num2str(i)];
disp(pesan)
end

toc

```

Lampiran 3: Script Matlab Pengolahan Data Mentah Menjadi Plot Domain Waktu

```

clear
clc

%Direktori tempat data mentah getaran berada
load('E:\Data Tugas Akhir\2. Data Pakai\2. Testing Data\1.
Normal\Tugas_AkhirNormal1_15.mat')

y1=data_all(:,1); %diberi nama dengan variabel baru dan berbeda untuk masing-
masing variasi bukaan katup

load('E:\Data Tugas Akhir\2. Data Pakai\1. Training Data\2. Rusak
Bola\Tugas_AkhirRusakBola_15.mat')

y2=data_all(:,1);

% plot amplitude time domain
figure
subplot(5,1,1)
plot(y1(1:25600))

```

```
axis([0 5000 -5 5])
legend('Normal')
xlabel('Sampel')
ylabel('Amplitudo')
```

```
subplot(5,1,2)
plot(y2(1:25600),'r')
axis([0 5000 -5 5])
legend('rusak')
xlabel('Sampel')
ylabel('Amplitudo')
```

Lampiran 4: Script Matlab Ekstraksi Parameter Statistik

```
clc
close all
clear

%Normal
for d=(1:500)
signal_in=['E:\Data Tugas Akhir\2. Data Pakai\1. Training Data\1.
Normal\Tugas_AkhirNormal1_',int2str(d),'.mat'];
load (signal_in)

a=data_all(:,1);
R(d)=rms(a);
S(d)=std(a);
P(d)=((max(abs(a))-min(abs(a)))/2);
```

```

K(d)=kurtosis(a);
V(d)=var(a);
C(d)=peak2rms(a);
M(d)=skewness(a);
x=1:500;

%rusak bola
for di=(1:500)

signal_in=['E:\Data Tugas Akhir\2. Data Pakai\1. Training Data\2. Rusak
Bola\Tugas_AkhirRusakBola_',int2str(di),'mat'];

load (signal_in)

b=data_all(:,1);
R1(di)=rms(b);
S1(di)=std(b);
P1(di)=((max(abs(b))-min(abs(b)))/2);
K1(di)=kurtosis(b);
V1(di)=var(b);
C1(di)=peak2rms(b);
M1(di)=skewness(b);
x1=1:500;

%R
figure
s=14;
c='r';
scatter(x,(R),s,c,'v');

```

```

hold on
s=14;
c='b';
scatter(x1,(R1),s,c,'x');
hold on

axis([0 500 0 1.5])
title('Grafik RMS')
xlabel('Sampel'),ylabel('Amplitudo')
legend ('Normal','Rusak')

%S
figure
s=14;
c='r';
scatter(x,(S),s,c,'v');
hold on
s=14;
c='b';
scatter(x1,(S1),s,c,'x');
hold on

axis([0 500 0 1.5])
title('Grafik Standar Deviasi')
xlabel('Sampel'),ylabel('Amplitudo')
legend ('Normal','Rusak')

%P

```

```

figure
s=14;
c='r';
scatter(x,(P),s,c,'v');
hold on
s=14;
c='b';
scatter(x1,(P1),s,c,'x');
hold on

axis([0 500 0 3.5])
title('Grafik Peak Value')
xlabel('Sampel'),ylabel('Amplitudo')
legend ('Normal','Rusak')

```

```

%K
figure
s=14;
c='r';
scatter(x,(K),s,c,'v');
hold on
s=14;
c='b';
scatter(x1,(K1),s,c,'x');
hold on

axis([0 500 2.5 4])
title('Grafik Kurtosis')

```



```
xlabel('Sampel'),ylabel('Amplitudo')
```

```
legend ('Normal','Rusak')
```

```
%V
```

```
figure
```

```
s=14;
```

```
c='r';
```

```
scatter(x,(V),s,c,'v');
```

```
hold on
```

```
s=14;
```

```
c='b';
```

```
scatter(x1,(V1),s,c,'x');
```

```
hold on
```

```
axis([0 500 0 2])
```

```
title('Grafik Varians')
```

```
xlabel('Sampel'),ylabel('Amplitudo')
```

```
legend ('Normal','Rusak')
```

```
%C
```

```
figure
```

```
s=14;
```

```
c='r';
```

```
scatter(x,(C),s,c,'v');
```

```
hold on
```

```
s=14;
```

```
c='b';
```

```
scatter(x1,(C1),s,c,'x');
```

```

hold on

axis([0 500 4 6])
title('Grafik Crest Factor')
xlabel('Sampel'),ylabel('Amplitudo')
legend ('Normal','Rusak')

```

```

%M
figure
s=9;
c='r';
scatter(x,(M),s,c,'v');
hold on
s=9;
c='b';
scatter(x1,(M1),s,c,'x');
hold on

```

```

axis([0 500 -0.01 0.01])
title('Grafik Skewness')
xlabel('Sampel'),ylabel('Amplitudo')
legend ('Normal','Rusak')

```

Lampiran 1: Script Matlab Principal Component Analysis (PCA)

```

vector_ch1234(:,1)=Normaltra;

```

```

vector_ch1234(:, :, 2) = Rusaktra;

for i = 1:2

    eval (
    ['[LOADING_ch', int2str(i), ', SCORE_ch', int2str(i), ', latent_ch', int2str(i), ', T2_ch', int
    2str(i), '] = princomp(zscore(vector_ch12(:, :, ', int2str(i), '));)');

    eval ( ['norm_vector_ch12(:, :, ', int2str(i), '), MU(i, :), SIGMA(i, :) =
    zscore(vector_ch12(:, :, ', int2str(i), ')); '])

    eval ( ['loading(:, :, ', int2str(i), ') = LOADING_ch', int2str(i), ';'])

    eval ( ['score(:, :, ', int2str(i), ') = SCORE_ch', int2str(i), ';'])

    eval ( ['latent(:, ', int2str(i), ') = latent_ch', int2str(i), ';'])

end

figure()
pareto(LATENT)
xlabel('Principal Component')
ylabel('Variance Explained (%)')

```

Lampiran 5 : Spesifikasi Accelerometer

Calibration Chart for DeltaTron[®] Accelerometer Type 4507 B
 Serial No.: ...30172

Reference Sensitivity¹⁾ at 159.2 Hz ($\omega = 1000 \text{ s}^{-1}$): 20 ms^{-2} RMS;
 4 mA supply current and 24.0 °C: ...3.953 mV/ms^2 (.....9.7.....60 mV/g)
 Frequency Range:2.....0.3 Hz to 6 kHz;
 Amplitude ($\pm 10\%$):2.....0.3 Hz to 5 kHz;
 Phase ($\pm 5^\circ$):2.....

Mounted Resonance Frequency: 18 kHz
Transverse Sensitivity²⁾: Maximum (at 30 Hz, 100 ms^{-2}):
Transverse Resonance Frequency: < 5% re Reference Sensitivity
 Calculated values for TEDS³⁾: > 18 kHz
 Resonance frequency: 20.2 kHz
 Quality factor Q_{res} : 1.4
 Amplitude slope: -2.1%/decade
 High pass cut-off frequency: 0.046 Hz
 Low pass cut-off frequency: 1.41 kHz
 ± 700 ms^{-2} peak ($\pm 71 \text{ g peak}$)

Measuring Range: Polarity of the electrical signal is positive for an acceleration in the direction of the arrow on the drawing.

Electrical:
 Bias Voltage: at full temperature and current range: +13 V $\pm 1 \text{ V}$
 Power Supply requirements: Constant Current: +2 to +20 mA
 Unbounded Supply Voltage: +24 V to +30 V
 Output Impedance: < 30 Ω
 Start-up time (to final bias $\pm 10\%$): 5 s
 Inherent Noise (RMS): < 35 μV
 Broadband (1 Hz to 6 kHz): corresponding to < 0.0035 ms^{-2} (< 350 μg)
 10 Hz: $1.5 \times 10^{-7} \text{ ms}^{-2}/\text{Hz}$ ($15 \mu\text{g}/\text{Hz}$)
 100 Hz: $3.5 \times 10^{-7} \text{ ms}^{-2}/\text{Hz}$ ($3.5 \mu\text{g}/\text{Hz}$)
 Spectral: 2 $\times 10^{-7} \text{ ms}^{-2}/\text{Hz}$ ($2 \mu\text{g}/\text{Hz}$)

Ground Loops can introduce error signals. These can be avoided by insulating the accelerometer from the mounting surface (see Mounting technique).
Recommended cables: AO 1382
 AO 0531
 and other cables see Product Data Sheet

Built-in ID-information according to IEEE P1451.4

Environmental:
 Temperature Range: -54 to +121°C (-65 to +250°F)
 Temperature Coefficient of Sensitivity: +0.09%/°C
 Temp. Transient Sensitivity (3 Hz Low Lim. Freq. (3 dB, 6 dB/oct)): 0.2 $\text{ms}^{-2}/\text{°C}$
 3 $\text{ms}^{-2}/\text{°C}$
 Magnetic Sensitivity (50 Hz, 0.038 T): 0.005 $\text{ms}^{-2}/\mu\text{T}$
 Base Strain Sensitivity (at 250 μe in base plane): 50 kms^{-2} peak (5000 g peak)
 Mounted on adhesive tape 0.09 mm thick:
 Max. Non-destructive Shock: 90% RH non-condensing
 Humidity:

Mechanical:
 Case Material: Titanium ASTM Grade 2
 Sensing Element: Piezoelectric, Type PZ 23
 Construction: Theta Shear⁴⁾
 Sealing: Welded
 Weight: 4.8 gram (0.17 oz)
 Electrical Connector: 10 - 32 UNF-2A
 Mounting Surface Finishes: < 3 μm

Mounting Techniques:
 The measuring object to be measured directly to the measuring object by glue e.g., hot glue. However, if a reduced frequency range can be accepted, the measuring object can be used. In any case the mounting surface must be clean and smooth. Three types of mounting clips are available. DA 1407 (set of 100) is a low profile clip with a swivel base clip for use where the accelerometer is to be aligned according to a given co-ordinate system (see Product Data Sheet BP 1841). DA 1428 (set of 100) is a thick base clip which can be filled to fit a curved mounting surface. DA 1428 (set of 100) is a swivel base clip for use where the accelerometer is to be aligned according to a given co-ordinate system (see Product Data Sheet BP 1841). Applying a little grease to the mounting surface of the accelerometer as well as the measuring object will improve the frequency response. See also ISO 5348.

Frequency Response generated from individual TEDS³⁾ values

Typical Low Frequency Response

Dimensions:
 Centre of gravity of seismic mass: 10 mm
 Centre of gravity of accelerometer: 10 mm
 Direction of acceleration: Indicated by arrow in drawing
 Dimensions: 10 mm x 10 mm x 4.2 mm (height)
 5.6 mm (width)
 0.75 mm (thickness)
 All dimensions in millimetres

Serial No.: 30172
 Date 02 Jun 2007, 13:24 Operator: JHR
 Specifications obtained in accordance with ANSI Z39-18 and parts of ISO 5347.
 All values are typical at 25°C (77°F) unless measurement uncertainty is specified.
 BC 0288-12