

## LAMPIRAN PERHITUNGAN

### 1.Perhitungan Regresi Linear

Data ke	x	y	xy	x <sup>2</sup>	y <sup>2</sup>
1	0	0	0	0	0
2	2	1	2	4	1
3	59	2	118	3481	4
4	132	3	396	17424	9
5	220	4	880	48400	16
6	285	5	1425	81225	25
7	370	6	2220	136900	36
<b>Jumlah</b>	<b>1068</b>	<b>21</b>	<b>5041</b>	<b>287434</b>	<b>91</b>

x : nilai pulsa yang keluar oleh sensor waterflow

y : nilai flowrate yang di atur pada regulator oksigen (L/menit)

n : jumlah data

$$b = \frac{n \sum xy - \sum x \sum y}{n \sum x^2 - (\sum x)^2}$$

$$b = \frac{(7 \cdot 5041) - (1068 \cdot 21)}{(7 \cdot 287434) - (1068^2)}$$

$$b = \frac{12859}{871414}$$

$$b = 0,0147$$

$$a = y - b x$$

$$a = 1 - (0,0147 \cdot 2)$$

$$a = 0,970$$

$$Y = a + b X$$

$$Y = 0,970 + 0,0147 (59)$$

$$Y = 1,841$$

Maka rumus fungsi regresi linear adalah  $y = 0,0148 (x) + 0,9704$

a. Laju aliran 1 L/menit

$$\begin{aligned} y &= 0,0148 (2) + 0,9704 \\ &= 1 \end{aligned}$$

b. Laju aliran 2 L/menit

$$\begin{aligned} y &= 0,0148 (59) + 0,9704 \\ &= 1,841 \end{aligned}$$

c. Laju aliran 3 L/menit

$$\begin{aligned} y &= 0,0148 (132) + 0,9704 \\ &= 2,918 \end{aligned}$$

d. Laju aliran 4 L/menit

$$\begin{aligned} y &= 0,0148 (220) + 0,9704 \\ &= 4,216 \end{aligned}$$

e. Laju aliran 5 L/menit

$$\begin{aligned} y &= 0,0148 (285) + 0,9704 \\ &= 5,176 \end{aligned}$$

f. Laju aliran 6 L/menit

$$\begin{aligned} y &= 0,0148 (370) + 0,9704 \\ &= 6,430 \end{aligned}$$

## Source code

```

#include <Wire.h>

#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27,
20, 4);

#include <Keypad.h>

const byte ROWS = 4;
const byte COLS = 4;

char hexaKeys[ROWS][COLS] =
{
  {'1', '2', '3', 'A'},
  {'4', '5', '6', 'B'},
  {'7', '8', '9', 'C'},
  {'*', '0', '#', 'D'}
};

byte rowPins[ROWS] = {3, 4,
5, 6};

byte colPins[COLS] = {7, 8,
9, 10};

Keypad customKeypad =
Keypad(
makeKeymap(hexaKeys),
rowPins, colPins, ROWS,
COLS);

char customKey;

float flowOksigen = 0.0;
int harga = 0, total_harga
= 0;

float mliter, liter;

boolean flag1 = 0;

byte flag2 = 0;

int detik, menit;

unsigned long i;

void(* resetFunc) (void) =
0;

ISR(TIMER1_OVF_vect)
// interrupt service
routine that wraps a user
defined function supplied
by attachInterrupt
{
  TCNT1 = 3036;

  if (flag2 == 1) {
    detik++;

    if (detik == 60) {
      menit++;
      detik = 0;
    }

    digitalWrite(12, 0);

    flowOksigen = (i * 0.0162)
+ 0.00; // liter Per menit

```

```

mliter += flowOksigen *
16.7;

liter = mliter / 1000;

total_harga = harga *
liter;

Serial.print(detik);

Serial.print("\tFlow
Oksigen :");

Serial.print(flowOksigen);

Serial.print("\tNilai I
:");

Serial.print(i);

Serial.print("\tHarga :");

Serial.print(harga);

Serial.print("\tTotal Harga
:");

Serial.print(total_harga);

Serial.print("\tmLiter :");

Serial.print(mliter);

Serial.print("\tLiter :");

Serial.println(liter);

i = 0;
}

else if (flag2 == 2) {
digitalWrite(12, 1);
}

}

void setup() {
// put your setup code
here, to run once:

cli();
Serial.begin(9600);
pinMode(A2, OUTPUT);
pinMode(A3, OUTPUT);
digitalWrite(A2, 0); // GND
lcd
digitalWrite(A3, 1); // VCC
lcd

pinMode(11, OUTPUT);
digitalWrite(11, 1); //VCC
relay

pinMode(12, OUTPUT);
digitalWrite(12, 1);

pinMode(2, INPUT_PULLUP);
// sensor flow

pinMode(A0, OUTPUT);
digitalWrite(A0, 0);

attachInterrupt(digitalPinT
oInterrupt(2), pulsa,
CHANGE); // interrupt

TCCR1A = 0;

TCCR1B = 0;

TCNT1 = 3036; //
preload timer 65536-
16MHz/256/1Hz

TCCR1B |= (1 << CS12); // |
(1 << CS10); // 256
prescaler

```

```

TIMSK1 |= (1 << TOIE1);
// enable timer overflow
interrupt

sei();

lcd.begin();

lcd.setCursor(0, 0);

lcd.print ("System Ready");

Serial.println("Masukan
Harga Oksigen !");

delay(3000);
}

unsigned long waktulama =
0;

void loop() {
// put your main code here,
to run repeatedly:

harga = getVal(); // harga
ngambil nilai dari keypad

if (harga) {
Serial.println(harga);
}
}

void pulsa() {
i++;
}

void tampil_lcd() {

if (millis() - waktulama >=
1000) {

waktulama = millis();
if (flag2 == 1) {
lcd.clear();

lcd.setCursor(0, 0);

lcd.print("FlowRate(L/m
:");

lcd.print(flowOksigen);

lcd.setCursor(0, 1);

lcd.print("Volume (L):");

lcd.print(liter);

lcd.setCursor(0, 2);

lcd.print("Waktu :");

lcd.print(menit);

lcd.print(" M");

lcd.setCursor(0, 3);

lcd.print("Harga : Rp. ");

lcd.print(total_harga);
}

if (flag2 == 0) {
lcd.clear();

lcd.setCursor(0, 0);

lcd.print ("Masukan Harga
O2 :");

lcd.setCursor(0, 1);

lcd.print("Rp. ");

lcd.print(harga);

lcd.print("/L");
}
}

long getVal() {

```

```

long value = 0;
customKey =
customKeypad.getKey();

while (customKey != '#') {
tampil_lcd();
switch (customKey)
{
case '0' : case '1': case
'2' : case '3': case '4':
case '5' : case '6': case
'7' : case '8': case '9':
value = value * 10 +
(customKey - '0');
break;

case '#':
return value;
break;

case 'D':
break;

case 'A':
flag2 = 1; //aktifkan relay
dan sensor
break;

case 'B':
flag2 = 2; // stop
digitalWrite(A0, 1); //
buzzer on

delay(2000);
digitalWrite(A0, 0); //
buzzer off
break;

case 'C':
resetFunc(); // buat reset
arduino
break;

case '*':
break;
}
customKey =
customKeypad.getKey();
}

return value;
}

```